






Customized Robots Parameter * ● Standard ○ Optional — None								
Product name	Dual belt robot	Dual roller robot	Lifting dual belt robot	Lifting roller robot	High position roller robot	Large roller robot	Composite robot	Latent traction robot
L*W*H(mm)	800*560*835	1000*700*850	720*560*1150	831*560*592.5	800*560*999	1000*1170*160	1000*600*800	800*560*297
Suitable material size(mm)		420*330	420*160	600*500	300*400	900*(650±5)	/	/
Load capacity(kg)	50*2	40*2	30*2	60*1	60*1	300*1	/	/
Transfer method	Single layer dual belt	Single layer dual roller	Single layer dual belt	Single layer single roller	Single layer single roller	Single layer single roller	Collaborative arm movements	Tract and release with the traction bar
Machine docking height(mm)	750±3	340±3	1065±3	551±3	960±3	680±2	/	/
Jacking height(mm)	/	/	60	60	/	/	/	47
Jacking time(mm/s)	/	/	12	12	/	/	/	12
Transfer speed(mm/min)	1.2-6 (Manually adjustable)	3.4-33.8(Manually adjustable)	5-15(Manually adjustable)	6-60.8 (Manually adjustable)	4-49.9 (Manually adjustable)	3.1-22.4 (Manually adjustable)	/	/
Shell color	RAL7035	RAL7035	RAL7035	RAL7035	RAL7035	RAL7035	RAL7035	RAL7035
Material in-position detection	Three groups of optoelectronics for each belt	Three groups of optoelectronics for each roller	Three groups of optoelectronics for each belt	Three groups of optoelectronics for each roller	Three groups of optoelectronics for each roller	Three groups of optoelectronics for each roller	/	/
Chassis	Based on AMB-150 series	Based on AMB-300 series	Based on AMB-150 series	Based on AMB-150 series	Based on AMB-150 series	Based on AMB-300 series	Based on AMB-300 series	Based on AMB-150 series

* Only common customized robots are listed here. For more details, please contact us to discuss.